

SUMMARY=ASYMPTOTIC STATISTICS-13-RANK

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Consider that we have N samples (X_1, \dots, X_N) .

1. REFERENCES

- (1) Asymptotic statistics メインテキスト
- (2) Theory of rank tests サブテキスト (明らかに上のテキストより詳しい)

2. WORDS

- (1) tie with 同じである。
- (2) remedy 修正する
- (3) subsequently その次に

3. DEFINITIONS

3.1. ordered statistics.

$$X_{N(1)} \leq \dots \leq X_{N(N)},$$

which makes a seq in the increasing order is an asymptotic case. If the asymptotic property is not considered, then we may write as follows in the same meaning:

$$X^{(1)} \leq \dots \leq X^{(N)}.$$

3.2. rank. R will stand for the vector of ranks (R_1, \dots, R_N) . r and (r_1, \dots, r_N) will be the realization of R , respectively. in the asymptotic case we use

$$R_{Ni}.$$

It is the position number of the i -th sample in N samples. The property is

$$X_i = X_{N(R_{Ni})}.$$

note1. If X_i is tied with some other observations, then we can not define the rank uniquely. In this case, we have two ways to solve this problem as follows:

- (1) Let $X_i = X_{N(j)}$ for all i , where X_i have the same value, and j is the average of all ranks that the sample takes;
- (2) Let $R_{Ni} = \sum_{j=1}^N 1_{\{X_j \leq X_i\}}$. (uprank)

However, we will assume the distribution from which the sample is is continuous. It means that the case will be a null set.

note2. the pair $(X^{(i)}, R)$ is a sufficient statistic for any system of distributions determined by densities.

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3.3. linear rank statistic.

$$\sum_{i=1}^N a_N(i, R_{Ni})$$

for a given $(N \times N)$ matrix $(a_N(i, j))$. This is the sum of the elements of the matrix $(a_N(i, j))$.

Example 1. Let $X = (2, 3, 1)$. Then

$$\begin{aligned} (1, R_{N1}) &= (1, 2) \\ (2, R_{N2}) &= (2, 3) \\ (3, R_{N3}) &= (3, 1). \end{aligned}$$

Thus, the position of the matrix can be shown as

$$\begin{pmatrix} a_{11} & a_{12} & \bigcirc \\ \bigcirc & a_{22} & a_{23} \\ a_{31} & \bigcirc & a_{33} \end{pmatrix}.$$

3.4. simple linear rank statistics.

$$\sum_{i=1}^N c_{Ni} a_{N, R_{Ni}};$$

This is a form of the sum of the elements of the matrix multiplied by some coefficients.

3.5. coefficients.

$$(c_{N1}, \dots, c_{NN});$$

3.6. scores.

$$(a_{N1}, \dots, a_{NN}).$$

3.7. i -th smallest coordinate. [not AS]

$$o_i(x),$$

and obviously $x^{(i)} = o_i(x)$.

3.8. the system where the distribution of (X_1, \dots, X_N) is symmetric and determined by a density.

$$p(x_{r_1}, \dots, x_{r_N}) = p(x_1, \dots, x_N), \quad r \in R,$$

if and only if $p \in H_*$.

3.9. the system where the observation is iid.

$$p = \prod_{i=1}^N f(x_i),$$

where $f(x)$ may be an arbitrary one-dimensional density if and only if $p \in H_0$. *note.* $H_0 \subset H_*$.

3.10. incomplete Beta function ratio $I_z(\mathbf{a}, \mathbf{b})$.

$$F(x) = I_x(a, b) = \frac{\int_0^x t^{a-1}(1-t)^{b-1} dt}{B(a, b)}, \quad 0 \leq x \leq 1; a, b > 0.$$

The mean of Beta distribution is $\frac{a}{a+b}$, the mode is $\frac{a-1}{a+b-2}$, the variance is $\frac{ab}{(a+b)^2(a+b+1)}$, the coefficient of variation is $\sqrt{\frac{b}{a(a+b+1)}}$, and the skewness is $\frac{2(b-a)\sqrt{a+b+1}}{(a+b+2)\sqrt{ab}}$

4. LEMMAS

Lemma 4.1. *If X is governed by the density q , then $X^{(\cdot)}$ is governed by the density*

$$\bar{q}(x^{(1)}, \dots, x^{(N)}) \triangleq \sum_{r \in R} q(x^{(r_1)}, \dots, x^{(r_N)}), \quad x^{(\cdot)} \in \mathbf{X}^{(\cdot)}.$$

Moreover,

$$Q(R=r|X^{(\cdot)}=x^{(\cdot)}) = \frac{q(x^{(r_1)}, \dots, x^{(r_N)})}{\bar{q}(x^{(1)}, \dots, x^{(N)})}, \quad r \in R, x^{(\cdot)} \in \mathbf{X}^{(\cdot)},$$

holds with Q being the probability distribution corresponding to q .

Proof. For any $A \in \mathcal{A}^{(\cdot)}$, it holds that

$$\begin{aligned} \int \cdots \int_{X^{(\cdot)} \in A} q(x_1, \dots, x_N) dx_1 \dots dx_N &= \sum_{r \in R} \int \cdots \int_{X^{(\cdot)} \in A, R=r} q(x_1, \dots, x_N) dx_1 \dots dx_N \\ &= \sum_{r \in R} \int \cdots \int_A q(x^{(r_1)}, \dots, x^{(r_N)}) dx^{(1)} \dots dx^{(N)} \end{aligned}$$

Note that the Jacobian is 1 in this case. □

note. \bar{q} do not have to be equal to each other. See the example following.

Example 2. *Let $\Omega = (1, 2, 3)$ and the probability on it is defined as*

$$(p_1, p_2, p_3) = \left(\frac{1}{4}, \frac{1}{4}, \frac{1}{2}\right).$$

After taking one sample from Ω , we will have the sample set like one of the following three cases:

$$\begin{aligned} \Omega' = (1, 3), \quad (p_1, p_3) &= \left(\frac{1}{3}, \frac{2}{3}\right); \\ \Omega' = (2, 3), \quad (p_2, p_3) &= \left(\frac{1}{3}, \frac{2}{3}\right); \\ \Omega' = (1, 2), \quad (p_1, p_2) &= \left(\frac{1}{2}, \frac{1}{2}\right). \end{aligned}$$

Then the probability for $(x^{(1)}, x^{(2)})$ will be $\frac{5}{12}$, and the probability for $(x^{(2)}, x^{(1)})$ will be $\frac{7}{12}$. Furthermore,

$$\begin{aligned}\bar{q}(1, 2) &= \frac{1}{6}; \\ \bar{q}(2, 3) &= \frac{5}{12}; \\ \bar{q}(1, 3) &= \frac{5}{12}.\end{aligned}$$

This example is a special case, and what we will think next is the property on the system 3.8 and 3.9.

Lemma 4.2. *Let X_1, \dots, X_N be a random sample from a continuous distribution function F with density f . Then*

- (1) *the vectors $X_{N()}$ and R_N are independent;*
- (2) *the vector $X_{N()}$ has density $N! \prod_{i=1}^N f(x_i)$ on the set $x_1 < \dots < x_N$;*
- (3) *the variable $X_{N(i)}$ has density $N \binom{N-1}{i-1} F(x)^{i-1} (1-F(x))^{N-i} f(x)$; for F the uniform distribution on $[0, 1]$, it has mean $i/(N+1)$ and variance $i(N-i+1)/((N+1)^2(N+2))$;*
- (4) *the vector R_N is uniformly distributed on the set of all $N!$ permutations of $1, 2, \dots, N$;*
- (5) *for any statistic T and permutation $r = (r_1, \dots, r_N)$ of $1, 2, \dots, N$,*

$$E(T(X_1, \dots, X_N) | R_N = r) = ET(X_{N(r_1)}, \dots, X_{N(r_n)});$$

- (6) *for any simple linear rank statistic $T = \sum_{i=1}^N c_{Ni} a_{N, R_{Ni}}$,*

$$ET = N\bar{c}_N \bar{a}_N; \quad \text{Var} T = \frac{1}{N-1} \sum_{i=1}^N (c_{Ni} - \bar{c}_N)^2 \sum_{i=1}^N (a_{Ni} - \bar{a}_N)^2.$$

Proof.

- (1) It is obvious from Lemma 1.
- (2) The same as the above.
- (3)
- (4)
- (5) Just change the rotation of the random variables, then we can see it by the virtue of the independence between $X_{N()}$ and R_N .

□

note. Even we suppose the density is identical, (1), (2), (5) of the lemma hold even in the case of 3.8.

Corollary 4.3. *As the same condition, the variable $X_{N(i)}$ has density*

$$F_{N(i)}(x) = I_{F(x)}(i, N-i+1) = \frac{N!}{(i-1)!(N-i)!} \int_0^{F(x)} u^{i-1} (1-u)^{N-i} du.$$

5. A NECESSARY CONDITION FOR RANK STATISTICS ASYMPTOTICALLY NORMAL

The scores are generated through a given function $\phi : [0, 1] \rightarrow \mathbb{R}$ in one of two ways. Either

$$(5.1) \quad a_{Ni} = E\phi(U_{N(i)}),$$

where $U_{N(1)}, \dots, U_{N(N)}$ are the order statistics of a sample of size N from the uniform distribution on $[0, 1]$; or

$$(5.2) \quad a_{Ni} = \phi\left(\frac{i}{N+1}\right).$$

For well-behaved functions ϕ , these two definitions are closely related and almost identical, since $EU_{N(i)} = \frac{i}{N+1}$.

note. Scores of the first type correspond to the locally most powerful rank tests; scores of the second type are attractive in view of their simplicity.

6. PROPERTY OF RANK STATISTICS

Theorem 6.1. *Let R_N be the rank vector of an i.i.d. sample X_1, \dots, X_N from the continuous distribution function F . Let the scores a_N be generated according to (??) for a measurable function ϕ that is not constant almost everywhere, and satisfies $\int_0^1 \phi^2(u) du < \infty$. Define the variables*

$$T_N = \sum_{i=1}^N c_{Ni} a_{N, R_{Ni}}, \quad \tilde{T}_N = N \bar{c}_N \bar{a}_N + \sum_{i=1}^N (c_{Ni} - \bar{c}_N) \phi(F(X_i)).$$

Then the sequences T_N and \tilde{T}_N are asymptotically equivalent in the sense that

•

$$ET_N = E\tilde{T}_N$$

•

$$\frac{\text{Var}(T_N - \tilde{T}_N)}{\text{Var}T_N} \rightarrow 0$$

The same is true if the scores are generated according to (??) for a function ϕ that is continuous and almost everywhere, is nonconstant, and satisfies

$$\frac{1}{N} \sum_{i=1}^N \phi^2\left(\frac{i}{N+1}\right) \rightarrow \int_0^1 \phi^2(u) du < \infty.$$

Theorem 6.2 (Lindeberg-Feller central limit theorem). *For each n let $Y_{n,1}, \dots, Y_{n,k_n}$ be independent random vectors with finite variances such that*

$$\sum_{i=1}^{k_n} E\|Y_{n,i}\|^2 1\{\|Y_{n,i}\| > \epsilon\} \rightarrow 0, \quad \text{for every } \epsilon > 0,$$

$$\sum_{i=1}^{k_n} \text{Cov}Y_{n,i} \rightarrow \Sigma.$$

Then

$$\sum_{i=1}^{k_n} (Y_{n,i} - EY_{n,i}) \xrightarrow{d} \mathcal{N}(0, \Sigma).$$

Note that

$$(6.1) \quad \frac{\max_{1 \leq i \leq N} (c_{Ni} - \bar{c}_N)^2}{\sum_{i=1}^N (c_{Ni} - \bar{c}_N)^2} \rightarrow 0.$$

Corollary 6.3. *If the vector of coefficients c_N satisfies (??), and the scores are generated according to (??) for a measurable, nonconstant, square-integrable function ϕ , then the sequence of standardized rank statistics*

$$\frac{(T_N - ET_N)}{\text{sd}T_N} \xrightarrow{d} \mathcal{N}(0, 1).$$

The same is true if the scores are generated by (??) for a function ϕ that is continuous almost everywhere, is nonconstant, and satisfies

$$\frac{1}{N} \sum_{i=1}^N \phi^2\left(\frac{i}{N+1}\right) \rightarrow \int_0^1 \phi^2(u) du.$$

7. SIGNED RANK STATISTICS

Lemma 7.1. *Let X_1, \dots, X_N be a random sample from a continuous distribution that is symmetric about 0. Then*

- (1) *the vectors $(|X|, R_N^+)$ and $\text{sign}_N(X)$ are independent;*
- (2) *the vector R_N^+ is uniformly distributed over $\{1, \dots, N\}$;*
- (3) *the vector $\text{sign}_N(X)$ is uniformly distributed over $\{-1, 1\}^N$;*
- (4) *for any signed rank statistic, $\text{Var} \sum_{i=1}^N a_{N, R_{Ni}^+} \text{sign}(X_i) = \sum_{i=1}^N a_{Ni}^2$.*

Theorem 7.2. *Let X_1, \dots, X_N be a random sample from a continuous distribution that is symmetric about 0. Let the scores a_N be generated according to (??) for a measurable function ϕ such that $\int_0^1 \phi^2(u) du < \infty$. For F^+ the distribution function of $|X_1|$, define*

$$T_N = \sum_{i=1}^N a_{N, R_{Ni}^+} \text{sign}(X_i), \quad \tilde{T}_N = \sum_{i=1}^N \phi(F^+(|X_i|)) \text{sign}(X_i).$$

Then the sequences T_N and \tilde{T}_N are asymptotically equivalent in the sense that $\frac{1}{N} \text{Var}(T_N - \tilde{T}_N) \rightarrow 0$. Consequently, the sequence

$$N^{-1/2} T_N \xrightarrow{d} \mathcal{N}\left(0, \int_0^1 \phi^2(u) du\right).$$

The same is true if the scores are generated according to (??) for a function ϕ that is continuous almost everywhere and satisfies

$$\frac{1}{N} \sum_{i=1}^N \phi^2\left(\frac{i}{N+1}\right) \rightarrow \int_0^1 \phi^2(u) du.$$

8. RANK STATISTICS UNDER ALTERNATIVES

8.1. smooth score-generating functions. Let \bar{F}_N be the average of F_1, \dots, F_N and let \bar{F}_N^c be the weighted sum $N^{-1} \sum_{i=1}^N c_{Ni} F_i$, and define

$$T_N = \sum_{i=1}^N c_{Ni} \phi\left(\frac{R_{Ni}}{N+1}\right), \quad \hat{T}_N = \sum_{i=1}^N \left[c_{Ni} \phi(\bar{F}_N(X_i)) + \int_{X_i}^{\infty} \phi'(\bar{F}_N(x)) d\bar{F}_N^c(x) \right].$$

Here, the variables \hat{T}_N are the Hájek projections of approximations to the variables T_N , up to centering at mean 0. (あくまでも近似で、ちゃんとした projection については、結果はよりよいが、形はもっと煩雑である。)

Lemma 8.1. *If $\phi : [0, 1] \mapsto \mathbb{R}$ is twice continuously differentiable, then there exists a universal constant K such that*

$$\text{Var}(T_N - \hat{T}_N) \leq K \frac{1}{N} \sum_{i=1}^N (c_{Ni} - \bar{c}_N)^2 (\|\phi'\|_{\infty}^2 + \|\phi''\|_{\infty}^2).$$

note. As a consequence of the lemma, the sequences

$$\frac{T_N - ET_N}{\text{sd}T_N} \quad \text{and} \quad \frac{\hat{T}_N - E\hat{T}_N}{\text{sd}\hat{T}_N}$$

have the same limiting distribution (if any) if

$$\frac{\sum_{i=1}^N (c_{Ni} - \bar{c}_N)^2}{N \text{Var}\hat{T}_N} \rightarrow 0.$$

Lemma 8.2 (Variance Inequality). *For nondecreasing coefficients $a_{N1} \leq \dots \leq a_{NN}$ and arbitrary scores c_{N1}, \dots, c_{NN} ,*

$$\text{Var} \sum_{i=1}^N c_{Ni} a_{N,R_{Ni}} \leq 21 \max_{1 \leq i \leq N} (c_{Ni} - \bar{c}_N)^2 \sum_{i=1}^N (a_{Ni} - \bar{a}_N)^2.$$

Theorem 8.3 (Rank central limit theorem). *Let $T_N = \sum c_{Ni} a_{N,R_{Ni}}$ be the simple linear rank statistic with coefficients and scores such that*

$$\begin{aligned} \max_{1 \leq i \leq N} \frac{|a_{Ni} - \bar{a}_N|}{\sum_{i=1}^N (a_{Ni} - \bar{a}_N)^2} &\rightarrow 0; \\ \max_{1 \leq i \leq N} \frac{|c_{Ni} - \bar{c}_N|}{\sum_{i=1}^N (c_{Ni} - \bar{c}_N)^2} &\rightarrow 0. \end{aligned}$$

Let the rank vector R_N be uniformly distributed on the set of all $N!$ permutations of $\{1, 2, \dots, N\}$. Then the sequence

$$\frac{T_N - ET_N}{\text{sd}T_N} \xrightarrow{d} \mathcal{N}(0, 1),$$

if and only if, for every $\epsilon > 0$,

$$\sum_{(i,j): \sqrt{N}|a_{Ni}-\bar{a}_N||c_{Ni}-\bar{c}_N| > \epsilon A_N C_N} \frac{|a_{Ni} - \bar{a}_N|^2 |c_{Ni} - \bar{c}_N|^2}{A_N^2 C_N^2} \rightarrow 0,$$

where

$$A_N^2 = \sum_{i=1}^n (a_{Ni} - \bar{a}_N)^2, \quad C_N^2 = \sum_{i=1}^N (c_{Ni} - \bar{c}_N)^2.$$

9. MAIN IDEAS

- (1) Rank test is used to test hypotheses.
- (2) Generally, the null hypothesis is to assume the r.v. is iid.
- (3) The virtue of using rank test is that it is distribution free.
- (4) Rank test is a special example of permutation test.